# Sphere eversions & the h-principle

#### Lauran Toussaint - VU General Math Colloquium



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- Control theory; Robots
- Geometric structures; Symplectic and contact structures

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H-principle approach: look at the space of all solutions at once.

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 $\Rightarrow$  homotopy: Allow solutions to be continuously deformed.

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A map is an **immersion** if its differential is injective.

This implies:

- Can have self intersections.
- No cusps, creases or pinches.



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Rotation number is invariant under regular homotopy.

## Question:

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• The naive try does not work due to cusps:



Smale '59

#### Smale '59 $\longrightarrow$ Bott













In fact, Smale's paper contains no pictures at all. The intricacy of the pictures, which were in a sense implicit in Smale's abstract and analytical mathematics, is amazing. Perhaps even more amazing is the ability of mathematicians to convey these ideas to one another without relying on pictures. This ability is strikingly brought out by the history of Shapiro's description of how to turn a sphere inside out. I learned of its construction from the French topologist René Thom, who learned of it from his colleague Bernard Morin, who learned of it from Arnold Shapiro himself. Bernard Morin is blind.



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Regular homotopic to standard cylinder?





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Philips figured out how to complete the movie.

Philip's pictures:






























































































































# What happens to the rest of the surface?











































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#### Fun facts

- Many more eversions have been found.
- ▶ Only spheres which can be turned inside out are: S<sup>0</sup>, S<sup>2</sup>, S<sup>6</sup>.
- Any (genus g) surface can be turned inside out. For example, torus:



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• Holonomic sections: Given f we get a section  $j^r f : M \to J^r(M, \mathbb{R})$ 

$$x \mapsto (x, T(x), T(x), T(x), \dots).$$

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## Example

Differential equation:

$$F(x, f, \dot{f}) := \dot{f}(x)^3 + 4f(x) - 6x - 11 = 0$$

induces

$$\mathcal{R}_F := \{(x, y, z) \mid F(x, y, z) = 0\} \subset J^1(\mathbb{R}, \mathbb{R}) \simeq \mathbb{R}^3$$

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$$J^1(\mathbb{S}^2,\mathbb{R}^3)\simeq \mathbb{S}^2 imes \mathbb{R}^3 imes M_{3 imes 2},$$
 and

$$\mathcal{R}_{\mathsf{Imm}(\mathbb{S}^2,\mathbb{R}^3)} = \{(x, y, A) \mid \mathsf{rank}\, A = 2\}.$$

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▶ Formal solutions:  $Sol_{\mathcal{R}}^{f}(M) := \{sections f : M \to \mathcal{R}\}.$ 

$$f^2+\dot{f}^2-1=0 \ \rightsquigarrow \ \mathcal{R}:=\{x^2+y^2+1=0\}\subset J^1(\mathbb{R},\mathbb{R}),$$

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 ${\cal R}$  satisfies the **h-principle** if  $\iota_{{\cal R}}$  is an isomorphism (up to homotopy).

- Any formal solution is homotopic to a solution.
- Two solutions are homotopic if and only if they are homotopic as formal solutions.

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Is there a holonomic section approximating it?

 $\Rightarrow$  No, if  $\dot{f} < \varepsilon$  then

$$f(1)-f(0)=\int_0^1\dot{f}dx<\varepsilon.$$

# $\Rightarrow$ Add more space!



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 $\Rightarrow$  Now we can wiggle





Theorem (Gromov, Eliashberg-Mishachev)

Suppose we are given:

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- A wiggled version S of S;
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 $\Rightarrow$  if  $\mathcal{R}$  iso-invariant then f induces solution on M.



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Immersions  $\mathbb{S}^2 \to \mathbb{R}^3$  satisfy the h-principle.

• Microextension:  $\mathbb{S}^2 \times (-\varepsilon, \varepsilon)$  is open,  $\mathcal{R}_{\mathsf{imm}}$  is open and iso-invariant.



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- Microextension:  $\mathbb{S}^2 \times (-\varepsilon, \varepsilon)$  is open,  $\mathcal{R}_{imm}$  is open and iso-invariant.
- Fact: Any two immersions S<sup>2</sup> → R<sup>3</sup> are formally homotopic.
  ⇒ Smale's result.

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#### Theorem (del Pino, T.)

Any section  $M \to J^r(M, \mathbb{R})$  (with M open or closed) can be approximated by a singular holonomic multi-section.

$$\mathsf{Sol}(\mathcal{R}) \xrightarrow{\ \ "\iota_{\mathcal{R}}"} \mathsf{Sol}^f(\mathcal{R})$$





# Theorem (Fokma, del Pino, T.)

If  $\mathcal{R}$  is an open, isomorphism-invariant relation (on any M) then  $\operatorname{Sol}^{\operatorname{sing}}(\mathcal{R}) \to \operatorname{Sol}^{f}(\mathcal{R})$ 

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- Can also use it to simplify singularities.
- Resolving singularities much harder, sometimes possible.